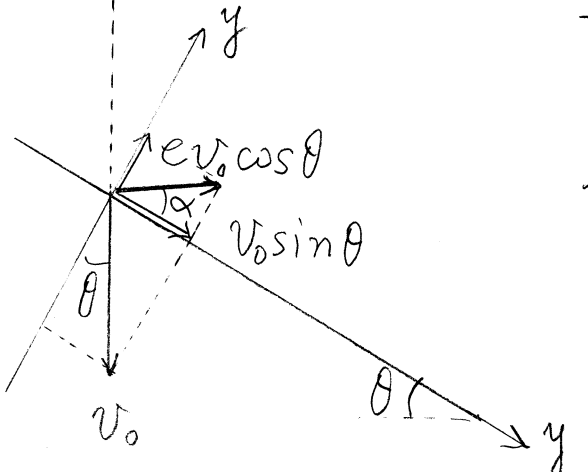
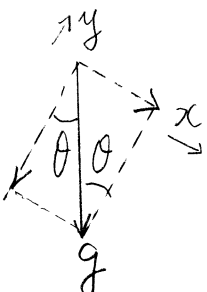
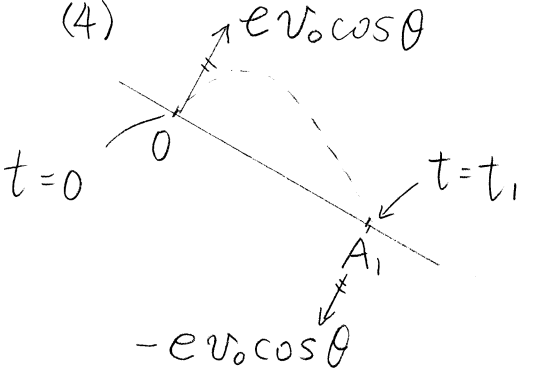


3 (1) $mg h = \frac{1}{2} m v_0^2$ $v_0 = \sqrt{2gh}$

(2)  x 成分 $\frac{\sqrt{2gh} \sin \theta}{}$
 y 成分 $\frac{e \sqrt{2gh} \cos \theta}{}$
 $\tan \alpha = \frac{e v_0 \cos \theta}{v_0 \sin \theta} = \frac{e}{\tan \theta}$

(3)  x 成分 $\frac{g \sin \theta}{}$
 y 成分 $\frac{-g \cos \theta}{}$

(4)  $-e v_0 \cos \theta = e v_0 \cos \theta - g \cos \theta \cdot t_1$
 $t_1 = \frac{2e v_0}{g} = \frac{2e}{g} \sqrt{2gh}$
 $= \frac{2e \sqrt{2h}}{g}$

$$OA_1 = v_0 \sin \theta \cdot t_1 + \frac{1}{2} g \sin \theta \cdot t_1^2$$

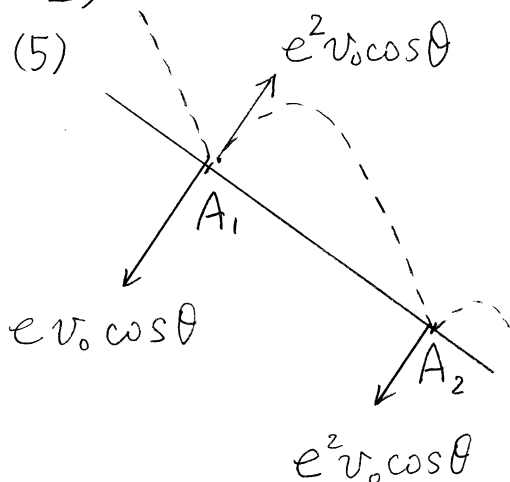
$$= \sqrt{2gh} \sin \theta \cdot \frac{2e \sqrt{2h}}{g} + \frac{1}{2} g \sin \theta \cdot 4e^2 \cdot \frac{2h}{g}$$

$$= 4eh \cdot \sin \theta + 4e^2 h \sin \theta$$

$$= \underline{4eh(1+e) \sin \theta}$$

(3-2)

(5)



(4)の t_1 から,

$$t_2 = \frac{2e^2 v_0}{g} = \underline{e t_1}$$

(6) 無限回はね返ると考える。OB間の時間を T とする。

$$T = t_1 + t_2 + t_3 + \dots$$

$$= (1 + e + e^2 + \dots) t_1$$

$$eT = (e^2 + e^3 + \dots) t_1$$

$$(1 - e)T = t_1 \quad T = \frac{t_1}{1 - e} = \frac{2e}{1 - e} \sqrt{\frac{2R}{g}}$$

$$OB = v_0 \sin \theta \cdot T + \frac{1}{2} g \sin \theta \cdot T^2 \quad (\text{x方向に等加速度運動})$$

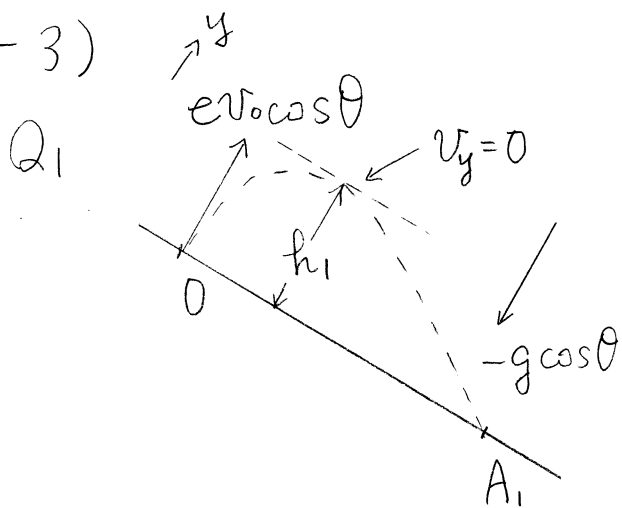
$$= \left\{ \sqrt{2gh} \cdot \frac{2e}{1 - e} \sqrt{\frac{2R}{g}} + \frac{1}{2} g \cdot \left(\frac{2e}{1 - e} \right)^2 \frac{2R}{g} \right\} \sin \theta$$

$$= \left\{ \frac{2e}{1 - e} \cdot 2R + \frac{2e}{1 - e} \cdot 2R \cdot \frac{e}{1 - e} \right\} \sin \theta$$

$$= \left\{ \frac{4eR}{1 - e} \left(1 + \frac{e}{1 - e} \right) \right\} \sin \theta$$

$$= \underline{\underline{\frac{4eR}{(1 - e)^2} \sin \theta}}$$

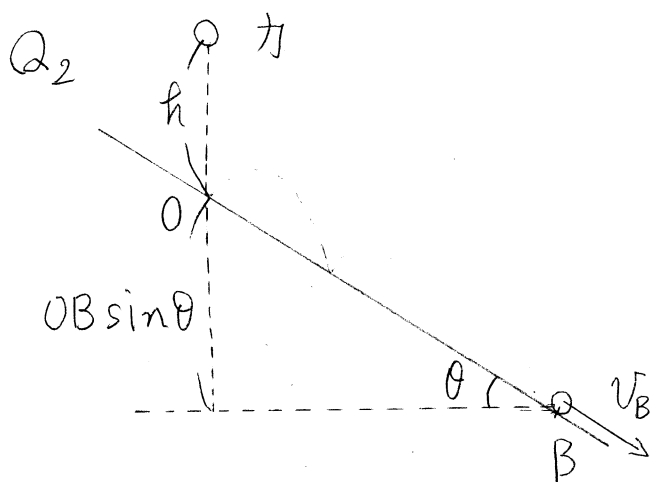
(3-3)



$$0^2 - (ev_0 \cos \theta)^2 = -2g \cos \theta \cdot h_1$$

$$h_1 = \frac{e^2 \times 2gh \times \cos^2 \theta}{2g \cos \theta}$$

$$= \underline{e^2 h \cos \theta}$$



$$v_B = v_0 \sin \theta + g \sin \theta \cdot T$$

$$= \left\{ \sqrt{2gh} + \frac{2e}{1-e} \sqrt{2gh} \right\} \sin \theta$$

$$= \frac{1+e}{1-e} \sqrt{2gh} \sin \theta$$

$$\Delta E = \frac{1}{2} m v_B^2 - mg(h + OB \sin \theta) \quad \left(\begin{array}{l} \text{失うエネルギー} \\ \text{後 - 前} \end{array} \right)$$

$$= \frac{1}{2} m \cdot \left(\frac{1+e}{1-e} \right)^2 \cdot 2gh \sin^2 \theta - mg \left\{ h + \frac{4eh}{(1-e)^2} \sin^2 \theta \right\}$$

$$= \left(\frac{1+e}{1-e} \right)^2 mgh \sin^2 \theta - mgh \left\{ 1 + \frac{4e}{(1-e)^2} \sin^2 \theta \right\}$$

$$= \frac{mgh}{(1-e)^2} \left\{ (1+2e+e^2) \sin^2 \theta - (1-2e+e^2) - 4e \sin^2 \theta \right\}$$

$$= \frac{mgh}{(1-e)^2} \left\{ (1-e)^2 \sin^2 \theta - (1-e)^2 \right\} = \underline{mgh \cos^2 \theta}$$

(注) x方向の等加速度運動について,

$$v_B^2 - (v_0 \sin \theta)^2 = 2g \sin \theta \cdot OB \quad \text{から,}$$

$\frac{1}{2} m v_B^2 = \frac{1}{2} m (v_0 \sin \theta)^2 + mgs \sin \theta \cdot OB$ とすると, ΔE の計算は簡単になる。